# Mate Model name: Ai Mate-I

Denjoy"

## **Endo Motor**



#### **Product parameters**

#### Adapter:

input voltage: A C 220V 50/60Hz

Output voltage: D C 5V Output current: 1A

Speed ratio: 6:1

Speed: 100-1000rpm

**Torque:** 0.2-5.0N.cm

Battery Capacity: 2000mAh

Reciprocate angle: 30-370°

Charging time: <2h



#### **Working Mode**



After starting, the fifile needle rotates 360° clockwise (1)

When the torque reaches the set torque, run the rotation action according to the set Angle (2/3);

Resume clockwise rotation when torque is less than the set value (1). Only clockwise rotation angle can be set, and counterclockwise rotation angle is half of clockwise rotation angle.



After starting, the fifile needle operates according to the set speed and reciprocating Angle. The maximum torque is not adjustable by default, the forward reciprocation and reverse reciprocation are realized by setting the Angle. Reciprocating motion fifile is recommended.



After starting, the fifile needle rotates 360° clockwise (①);

When the torque point action is set to "reverse", the buzzer will prompt when the torque is set, and the motor will rotate counterclockwise (②);

Rotate clockwise when torque is removed (1);

The torque point action is set to "stop", and the motor will stop rotating when the torque is set.



After starting, the fifile needle rotates 360° counterclockwise (①); When the torque point action is set to "reverse", the buzzer will prompt when the torque is set, and the motor will rotate clockwise (②);

Counterclockwise rotation will resume after torque is removed (①); The torque point action is set to "stop", and the motor will stop rotating when the torque is set.

# Ai-Mate Model name: Ai Mate-II

# Intelligent endo motor

- Black and white collocation, mature and steady
- Multifunction with simple operation
- Optimized algorithm, intelligent made



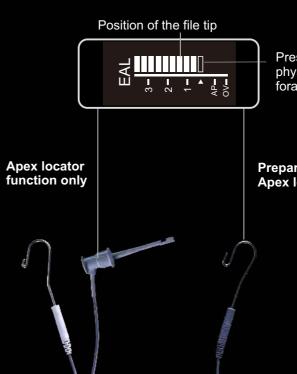


## **ACC Mode**

Ai-mate with the most advanced self-adaptive algorithms, you can do the preparation without setting, auto-optimized direction, speed and angle make efficiency & safety come true.

### 2 in 1 endo device

No need to shift the program when using double probe cord or single probe cord



Preset position of the physiological apical foramen

Preparation with Apex locating







#### 360° mini contra-angle with patent

Facilitate more operable teeth positions, avoid loosing after frequent use



#### USB-C

Charging, calibrating and apex locating all in one



#### Dominant hand shift

| 100-1000rpm |
|-------------|
| 0.2-5.0N.cm |
| 2000mAh     |
| 30-370°     |
| <2h         |
|             |

# Brand-new preparation with unique algorithm in Al era

No selection is the best choice

Adaptive cruise control, No need any settings



# **Operation Mode**



#### Adaptive Cruise Control

Adaptive algorithms are applied to this operation mode. The real time speed and torque load will be auto-optimized during the actual root canal preparation to minimize the risk of instrument broken.



#### Auto Oscillation Control

Continuous forward rotation normally, but when the load on the file exceeds the set limit, the file automatically oscillates alternately between forward  $240^\circ$  and reverse  $120^\circ$  (P6 default setting,only forward angle can be set), and rotates forward when the load on the file releases.



#### Reciprocation

Reciprocating with pre-set speed, angle, as well as default torque. Note: counterclockwise  $150^{\circ}+$  clockwise  $30^{\circ}$ is default. One file recommended.



#### Clockwise Mode

The motor rotates forward  $360^{\circ}$ 

Reverse: when the load on the file exceeds the set limit, beep sounds continuously, the file automatically reverses , and rotates forward when the load on the file releases. Stop: the file stops when the load on the file exceeds the set limit.



#### Counterclockwise Mode

The motor counterclockwise rotates 360°

Reverse: when the load on the file exceeds the set limit, beep sounds continuously,the file automatically rotates clockwise, and back to previous rotate direction when the load on the file releases.

Stop: the file stops when the load on the file exceeds the set limit.

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